

1 BACKGROUND OF THE INVENTION  
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34 FIELD OF THE INVENTION  
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6 The present invention relates generally to pressure  
7 regulation and self-contained breathing systems such as those  
8 used in scuba diving equipment and more specifically, to a new  
9 improved means for automatically altering the breathing  
10 characteristics of a demand-type regulator by automatic  
11 adjustment of the venturi action in the regulator in accordance  
12 with depth during diving.

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14  
15 PRIOR ART  
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17 Pressure regulators such as those employed in underwater  
18 breathing apparatus, utilize the pressure differential on  
19 opposite sides of a flexible diaphragm to operate an air valve  
20 which supplies air to a breathing chamber from which the diver  
21 breathes. Typically, such a flexible diaphragm is mounted to  
22 cover an opening in the wall of the breathing chamber whereby  
23 expansion of the diaphragm actuates the air valve. More  
24 specifically, when the diver inhales while the air inlet valve  
25 is closed, the pressure in the breathing chamber is reduced  
26 causing the diaphragm to bow inwards inside the breathing  
27 chamber and thereby allowing an air inlet valve to open. When  
28 the diver exhales, pressure in the chamber increases causing  
29 the diaphragm to move out to its original condition thereby  
30 closing the air inlet valve.

1      Recent prior art includes disclosure of various pressure  
2 regulator structures which provide a reduction in the effort  
3 required by the diver to breathe from such regulators. More  
4 specifically, regulators have been designed so that a portion  
5 of the inlet air travels into the breathing mouthpiece area in  
6 the form of a stream of air which produces a venturi effect.  
7 This venturi effect further reduces the pressures in the  
8 breathing chamber so that in effect the diver is not  
9 necessarily doing all the work required to sufficiently reduce  
10 the breathing chamber pressure to pull in and retain the  
11 diaphragm and cracking effort force setting whereby to open the  
12 air inlet valve. Thus, the venturi effect makes it easier for  
13 the diver to inhale air from the regulator. Breathing  
14 regulators which employ such venturi-type action to assist in  
15 responding to the breathing demand of the diver are highly  
16 advantageous. Unfortunately, they are not always optimally  
17 configured for the breathing requirements for each diver or for  
18 particular diving depths where ambient pressure increases as a  
19 function of depth thereby changing the parameters for the  
20 diver's degree of breathing difficulty and breathing  
21 requirements.

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23      In most scuba diving situations, the requirement for the  
24 second stage regulator can change. On the surface, the  
25 regulator must be stable. The second stage should not  
26 accidentally flow air without stopping on its own.  
27 Unfortunately, when a scuba regulator is tuned for stable  
28 surface operation (no venturi), the performance under deeper  
29 diving conditions can suffer. And if the regulator second  
30 stage is adjusted for deep diving, the surface performance can  
31 be too sensitive causing uncontrolled free flow of air forcing  
32 the scuba diver to manually stop the flow of air by blocking

1 the mouthpiece exit with his finger or glove.

2  
3 In response to this disadvantage of an otherwise advantageous  
4 concept, prior art patents have addressed various ways of  
5 altering venturi action in the regulator automatically during  
6 the breathing cycle. Thus, for example Patent No. 4,214,580 to  
7 Pedersen discloses a breathing apparatus of the venturi action  
8 regulator-type hereinabove discussed which utilizes an  
9 additional moving baffle to alter the venturi effect after the  
10 diver initially inhales. While such modification to the  
11 venturi action is accomplished automatically, it does not  
12 appear to be responsive to ambient water pressure variation  
13 with depth.

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15 Another prior art patent which addresses manual control  
16 aspect of venturi-type demand regulators is disclosed in Patent  
17 No. 4,147,176 to Christianson. This patent discloses the  
18 concept of using a conical platform in conjunction with a  
19 diaphragm wherein the diaphragm gradually flattens down against  
20 the platform to reduce the effect of sensing area during the  
21 breathing cycle. One embodiment is disclosed which has an  
22 adjustable aspirator which permits the diver to externally  
23 change the aspiration effect during the dive. Unfortunately,  
24 there is an inherent disadvantage in the manner in which the  
25 diaphragm and conical platform interact to control the venturi  
26 assist during the breathing cycle which makes the performance  
27 of the regulator substantially non-uniform during the breathing  
28 cycle. As a result, the diver may adjust the regulator  
29 characteristics to provide him with an advantageous operation  
30 for one aspect of the breathing cycle only to find that during  
31 another portion of the breathing cycle the adjustment is  
32 unsuitable.

1       U.S. Patent No. 3,526,241 to Veit is directed to an oxygen-  
2 air diluter for breathing apparatus employing an altitude  
3 controlled Venturi mixing mechanism. Referring to FIG. 1, the  
4 diluter apparatus is shown in its low altitude configuration  
5 with conically shaped valve member 24 sealing conical valve  
6 seat 18. Referring to FIG. 2, the diluter is shown in a high  
7 altitude configuration. Here, bellows 47 has expanded due to  
8 the lower air pressure exposed through aperture 49. Through  
9 the interaction of the associated elements, conically shaped  
10 valve member 24 is drawn away from conical valve seat 18,  
11 thereby permitting oxygen to enter Venturi throat portion 22  
12 from inlet 12.

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14       U.S. Patent No. 4,796,618 to Garrafffa is directed to a  
15 breathing regulator apparatus having a manually adjusted  
16 Venturi valve. Referring to FIG. 2, flow vane 22 is adjusted  
17 so that all or virtually all of the air stream 28 emanating  
18 from the air inlet valve 18 is directed into the mouthpiece  
19 tube 19. Referring to FIG. 3, the position of flow vane 22 has  
20 the effect of splitting the air stream 28 into two components,  
21 namely, a first component 30 which is directed towards the  
22 diaphragm 16 and a second component 32 which is directed  
23 through the mouthpiece tube 19.

24  
25       U.S. Patent No. 3,308,817 to Seeler is directed to a  
26 reduction regulator valve for a scuba system having an  
27 automatic depth controlled mixing adjustment system. Referring  
28 to the Drawings, when a diver descends into deeper water, the  
29 pressure exerted by the water within the end cap 25 on the  
30 bellows 49 will contract the bellows, which in turn will permit  
31 the coil spring 57 to extend, thereby lessening the pressure on  
32 the diaphragm 54, permitting the valve 36 to close under the

1 action of the valve spring 37. The reduction of the pressure  
2 exerted on the diaphragm 54 and the closing of the valve 36  
3 reduces the pressure exerted on the housing side of the  
4 diaphragm 63, permitting the spring 61 to press against the  
5 diaphragm 63 and urge the rod 64 against the valve 41, opening  
6 the passageway 65 to the tank containing a mixture of helium  
7 and oxygen to admit same to the outlet port 23 into the  
8 mouthpiece 73. Note, however, that this reference does not  
9 employ a Venturi action.

10

11 U.S. Patent No. 5,368,020 to Beux is directed to a depth  
12 controlled automatic mixing system for breathing apparatus.  
13 FIG. 7 shows a type B reducer which increases the flow of gas  
14 with increasing environmental pressure. This reducer comprises  
15 a body 200, a diaphragm 201 cooperating with a disk 202 which,  
16 by means of a mechanical connection member 203, cooperates with  
17 a further disk 204 associated with a diaphragm 205 which, by  
18 means of the disk 206 and the mechanical connection element  
19 207, cooperates with a plug 208. Stress is placed on the  
20 diaphragm 201 by environmental pressure, that is to say, by  
21 water pressure, which acts directly on the surface of the  
22 diaphragm 201 through the bore 209, providing the calibration  
23 thrust which varies according to environmental pressure.  
24 Through the flow restriction nozzle 212, the gas enters the  
25 tube 213 which sends it to the inspiration bag.

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1 Many scuba manufacturers solve the surface free flow problem  
2 by positioning a blade or vane near the air exit point of the  
3 second stage. The result is that air that travels out of the  
4 valve mechanism (located inside second stage) is blocked or re-  
5 routed back inside the second stage case before its velocity  
6 can create a venturi or free flow condition of the second  
7 stage.

8

9 These blades or vanes can also be manually re-positioned to  
10 allow rapid unobstructed air passage through the second stage  
11 causing the second stage to venturi assist (free flow). This  
12 venturi assist will increase the regulator performance by  
13 lowering the mechanical effort (or diver inhalation effort)  
14 required to breath the second stage.

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16 A disadvantage of the manual design is that the scuba  
17 regulator second stage is located in the mouth and held by the  
18 teeth by means of a rubber mouthpiece. Locating the manual  
19 switch is difficult and confusing. This adjustment is made by  
20 feel not sight when the regulator is in the mouth. These  
21 manual switches tend to be small and located in difficult  
22 locations to reach with the fingers. Also, divers that wear a  
23 thermally protecting glove cannot locate these manual switches.  
24 Sometimes the adjustment is so difficult to locate, the entire  
25 second stage must be removed from the mouth so the diver can  
26 see where the exact tuning position is with respect to  
27 incremental notching or indicator numbers. This is deemed an  
28 unsafe procedure. A better non-manual flow control is needed.

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1       There is, therefore, a need to provide a regulator which is  
2       of the breathing demand-type, which utilizes venturi assist to  
3       control the degree of air inlet opening, which provides the  
4       user with an automatic adjustment for varying the venturi  
5       effect during the dive and which, most importantly, provides  
6       either a constant or a smooth changing level of performance  
7       during the entire breathing cycle by adjustment for depth of  
8       the diver during the dive.

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## SUMMARY OF THE INVENTION

4 The present invention comprises an inhalation demand  
5 breathing regulator which solves the aforementioned need. More  
6 specifically, the present invention comprises a breathing  
7 regulator in which an automatically adjustable flow deflector  
8 or flow vane is utilized to create a diversion of high velocity  
9 air to direct it at the mouthpiece area of the regulator  
10 housing whereby to provide an automatic means for increasing  
11 the vacuum assist in demand regulators. When the flow vane is  
12 withdrawn, the air stream is redirected back into the housing,  
13 thus balancing the low pressure area behind the diaphragm which  
14 prevents a free flow condition and allows the demand regulator  
15 to be less sensitive to ambient water conditions. The  
16 automatic flow control, or A.F.C., is used in scuba diving  
17 regulator second stages to automatically regulate the venturi  
18 or aspirated flow of air to the diver at different depths.  
19 A.F.C. allows the regulator second stage to be stable on the  
20 surface (no venturi) and yet provides excellent performance at  
21 depth (maximum venturi) automatically freeing the diver of  
22 making any needed manual adjustments to the second stage under  
23 water. Unlike the prior art, the present invention does not  
24 depend upon the relative position of a diaphragm and for  
25 example, a conical platform which relationship varies non-  
26 linearly during a breathing cycle. The effect of the present  
27 invention is a venturi assisted demand regulator which is less  
28 complex in structure, more reliable and more predictable in  
29 performance and which varies automatically with depth  
30 increasing the venturi effect or assist level as the diver  
31 descends and reducing the venturi effect or assist level as the  
32 diver ascends.

## OBJECTS OF THE INVENTION

It is therefore a principal object of the present invention to provide an improved venturi assisted demand-type breathing regulator primarily for use in diving and which entirely overcomes or at least substantially reduces the deficiencies of the prior art.

10 It is an additional object of the present invention to  
11 provide a venturi assisted demand-type breathing regulator  
12 primarily for use by scuba divers wherein the extent to which  
13 the venturi action affects the air flow is automatically varied  
14 during the dive in accordance with the depth of the diver.

16 It is still an additional object of the present invention to  
17 provide a venturi assisted demand breathing regulator utilizing  
18 a deflector vane which, depending upon the position of the vane  
19 determined by ambient water pressure, increasingly deflects a  
20 portion of the air stream toward the mouthpiece thus increasing  
21 the venturi effect thereby allowing the demand regulator to be  
22 responsive to ambient water conditions.

24 It is still an additional object of the present invention to  
25 provide an automatically adjustable venturi assisted demand  
26 breathing regulator particularly advantageous for scuba diving  
27 wherein depth of the diver automatically adjusts a device for  
28 interfering with the air stream emanating from the inlet valve  
29 into the housing whereby the degree to which the venturi effect  
30 aids the diver's breathing may be automatically varied so that  
31 the breathing effort is compensated in accordance with the  
32 diver's depth.

#### BRIEF DESCRIPTION OF THE DRAWINGS

The aforementioned objects and advantages of the present invention as well as additional objects and advantages thereof will be more fully understood hereinafter as a result of a detailed description of a preferred embodiment of the invention when taken in conjunction with the following drawings in which:

10 FIG. 1 is a top cross-sectional view of the breathing  
11 regulator of the present invention configured for operation at  
12 the surface;

14 FIG. 2 is a similar top cross-sectional view of the invention  
15 illustrating the manner in which the invention automatically  
16 adjusts venturi effect for depth:

18 FIG. 3 is a side cross-sectional view of the breathing  
19 regulator illustrating air flow with automatic adjustment for  
20 surface operation; and

22 FIG. 4 is a similar side cross-sectional view of the  
23 breathing regulator illustrating air flow with automatic  
24 adjustment for operation at or near maximum depth.

## DESCRIPTION OF A PREFERRED EMBODIMENT

4 Referring first to FIG. 1 it will be seen that the improved  
5 breathing regulator apparatus 10 of the present invention  
6 comprises a demand valve 12 having an air inlet tube 13 which  
7 will be connected to a suitable source of pressurized air  
8 supply in a well-known manner. Apparatus 10 also comprises a  
9 diaphragm 16 cooperating with a lever 20 to selectively actuate  
10 the air inlet demand valve 12 in response to the breather's  
11 inhalation requirements. Lever 20 unseats a poppet 22 from an  
12 orifice 14 to open valve 12. Apparatus 10 also provides a  
13 mouthpiece tube 28 connected to a mouthpiece (not shown) which  
14 is normally retained within the mouth of the user permitting  
15 access to incoming air from air passage 26. Apparatus 10 also  
16 provides a piston-controlled deflector or flow vane 30 which  
17 comprises the critical component of the present invention as is  
18 hereinafter discussed. Apparatus 10 also comprises exhaust  
19 ports and an exhaust valve (not shown) which in combination,  
20 provide means for exhausting the exhalation gas of the user  
21 through the regulator 10.

23 The position of diaphragm 16 is determined by the relative  
24 pressure differential on opposing sides of the diaphragm within  
25 the diaphragm cover 18 and housing 19. The center of the  
26 diaphragm is provided with a bearing surface which bears  
27 against the lever 20 the position of which determines whether  
28 the air inlet valve 12 is opened or closed.

1 When the user begins to inhale through the mouthpiece tube  
2 28, the air pressure in the interior of the regulator is  
3 reduced. This reduction in the air pressure causes the central  
4 portion of diaphragm 16 to be sucked in towards the mouthpiece  
5 tube and compresses lever 20 and opens the air inlet valve 12.  
6 When the air inlet valve is opened, a stream of air is  
7 generated and flows through air exit 24 in the general  
8 direction of the mouthpiece tube 28 through the mouthpiece tube  
9 passage 26 thereby responding to the user's inhalation  
10 requirements, but also creating a venturi effect generated by  
11 the high velocity air emanating from the air inlet valve 12.  
12 This high velocity air pulls the still air inside the regulator  
13 along with it, causing a secondary pressure drop or a vacuum to  
14 exist inside the interior of the regulator.  
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16 The initial inhalation effort required to open the air inlet  
17 valve 12 is commonly referred to as the cracking effort. The  
18 extent of inhalation effort required after the cracking effort  
19 level has been reached depends on the extent to which the level  
20 of venturi assist is utilized during the remainder of the  
21 breathing cycle. In those prior art regulator devices in which  
22 virtually no further breathing effort is required, the user may  
23 incur a disadvantageous condition in which the air inlet valve  
24 remains open due to the venturi effect thus creating a  
25 condition of free flow which in effect forces air into the  
26 user's lungs. Such a condition may be desirable for the  
27 experienced diver under certain deep dive or other difficult  
28 breathing conditions. However, the less experienced diver may  
29 find such a free flow condition to be frightening or otherwise  
30 disadvantageous. For example, such free flow conditions  
31 occurring when the regulator is out of the mouth of the user  
32 can create a panicky environment for the diver who feels great

1 concern over the loss of air from his tanks.  
2

3 In any case, as previously noted, the relevant prior art has  
4 already disclosed means for manually changing the venturi  
5 assist effect whereby to overcome the noted disadvantages of  
6 those regulators which have employed full venturi assist  
7 configurations. The present invention however provides a novel  
8 means for automatically varying the venturi assist as a  
9 function of depth. More specifically, FIGS. 1 and 2 illustrate  
10 two different automatic adjustment configurations of the flow  
11 deflector tip or vane 30 of the present invention.  
12

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14 **AUTOMATIC FLOW CONTROL AT SURFACE OPERATION**  
15 (SEE FIGS. 1 and 3)

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17 Air from the first stage is passed through an air pressure  
18 hose to the orifice 14. As the diver demands air, the  
19 inhalation diaphragm 16 bows inward and forces the demand lever  
20 down moving the poppet 22 away from the orifice 14. Air  
21 travels past the poppet and exits from the air exit 24 and into  
22 the mouthpiece tube 28. Due to the position of the air exit,  
23 the exiting air cannot build up enough velocity to sustain a  
24 free flow venturi effect. The position of the deflector tip 30  
25 is retracted in its surface resting position. A piston  
26 comprising piston head 33 and piston rod 32 remains static by a  
27 low ambient pressure in a pressure cavity 38 which merely  
28 balances the pressure in a sealed pressure chamber 36. Spring  
29 34 assures retraction of the flow vane and the surface  
30 performance is stable due to no venturi, free flow.  
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1 As shown in FIG. 3, when the deflector tip 30 is in the  
2 retracted position at or near the surface or zero depth, the  
3 air stream bypasses the deflector tip. A significant portion  
4 of the air flow from air exit 24 is redirected toward the  
5 diaphragm after deflecting off of the top portion of the  
6 mouthpiece tube 28.

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9 AUTOMATIC FLOW CONTROL AT DEPTH OPERATION

10 (SEE FIGS. 2 and 4)

11

12 As the diver descends under water, ambient water pressure  
13 increases in the ambient water pressure cavity 38 and presses  
14 the piston head 33 and rod 32 forward, compressing the return  
15 spring 34 and increasing the pressure in the sealed pressure  
16 chamber 36. The deflector tip 30 now straightens the air  
17 leaving the air exit 24 thus creating a venturi effect and  
18 increasing regulator performance. As shown in FIG. 4, at  
19 significant depths, the deflector tip 30 enters the air stream  
20 deflecting a major portion toward the mouthpiece tube 28 and  
21 through the passage 26. This deflected flow creates a vacuum  
22 assist to bow the diaphragm 16 inwardly and lower the effort  
23 required to sustain flow. As the diver ascends back to the  
24 surface, the pressure is relieved from the ambient water  
25 pressure cavity 38 and the deflector tip 30 returns to its  
26 surface resting position and the second stage becomes stable  
27 once again. The O-rings 40 and 41 assure pressure integrity of  
28 chamber 36 and cavity 38 and retaining cap 42 secures return  
29 spring 34 and the piston.

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1        Thus it will be understood that the present invention  
2        provides a novel second stage scuba diving breathing regulator  
3        having automatic flow control wherein a venturi assist effect  
4        is automatically adjusted with depth to provide no venturi  
5        effect at the surface and an increasing venturi effect as the  
6        diver descends.

7  
8        Those having skill in the art to which the present invention  
9        pertains, will now, as a result of the disclosure herein,  
10       perceive various modifications which may be made to the  
11       invention. By way of example, the precise location and  
12       structure of the flow control mechanism may be altered while  
13       still achieving the novel objective of automatic flow control  
14       with depth of the diver as the variable parameter.  
15       Furthermore, the deflector tip of the invention may be  
16       configured to travel in either direction with increasing depth  
17       and thus alter air flow either proportional to depth or  
18       inversely proportional to depth. The latter configuration can  
19       be used to increase vacuum assist with increasing depth by  
20       altering the direction of the nominal air flow to provide more  
21       deflection away from the mouthpiece tube with increasing  
22       extension of the deflector tip at shallower depths. This would  
23       constitute a reversal of the disclosed embodiment while  
24       achieving the same result. Accordingly, all such modifications  
25       are deemed to be within the scope of the invention which is to  
26       be limited only by the appended claims and their equivalents.

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28       I  
29       (We) claim:

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